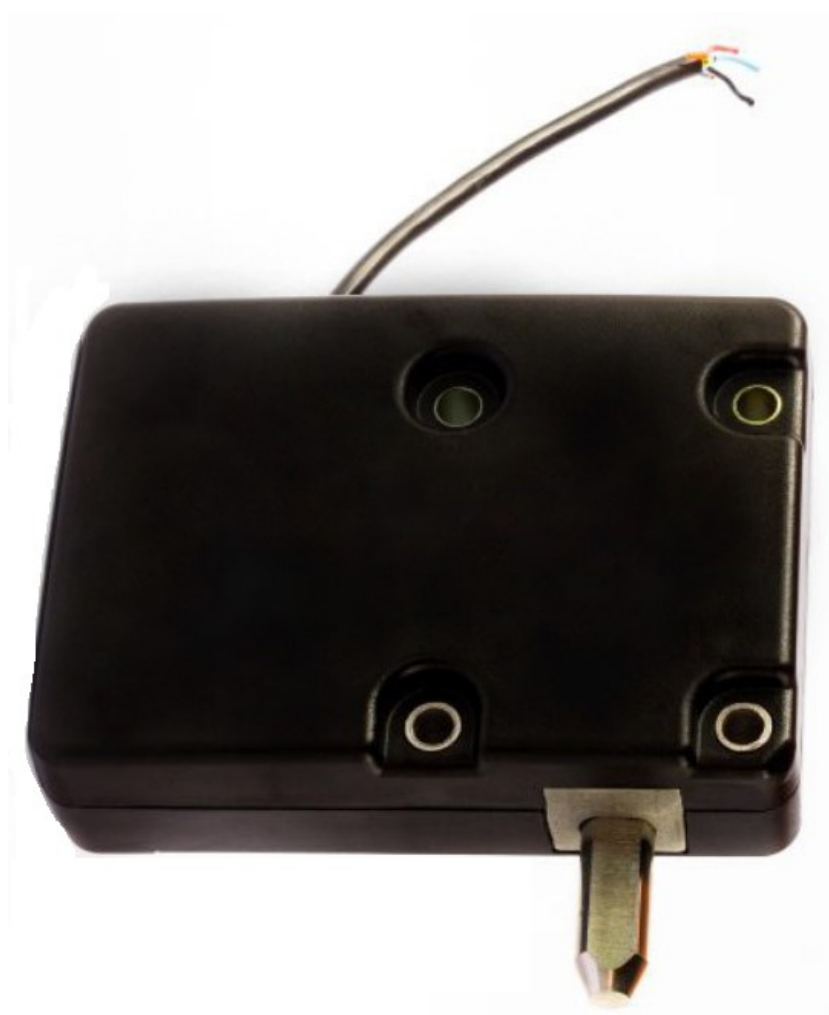




**DATASHEET**  
**ELECTROMECHANICAL ACTUATOR**  
**(electronic locking device)**

**Product code: 550.100.000.1236**



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## **INTRODUCTION**

Electromechanical actuator (Electronic Lock) was designed for remote internal locking doors or gates by help of suitable controller or telematics terminal unit.

The device is dedicated for operation in harsh environment conditions and was created in collaboration with security and telematics service operators.

The gearmotor steel pin assembly supports the intensive use by those who make dozens of openings per day. The electronic parts are sealed by the silicone compound, that provides an extraordinary protection against dust, humidity and low temperature also allowing the use of high pressure washers when cleaning refrigerated environments.

## **Application**

The device is intended for remote locking /unlocking doors or gates of cargo trailers, box trucks, refrigerators, containers, shelters and cabinets for various telecommunication, electrical, control equipment and instruments.

## Wiring legend

Wire color	Description	Connection
<b>Red</b>	Power supply	VCC(+)
<b>Black</b>	Power supply	GND (-)
<b>Blue</b>	Control signal	Positive polarity (VCC) / negative polarity (GND)
<b>Brown</b>	Locked/Unlocked status signal	Logical input (Low-High)

### Control signal (polarity) applied to BLUE wire

VOLTAGE (POLARITY)	LOCK's ACTION
- GND (NEGATIVE) signal (command) (permanently connected)	LOCKING (pin is drawn out)
NOT CONNECTED or permanently disconnected	LOCKING (pin is drawing out)
+ VCC (positive) not earlier than 10 seconds after applied control signal (command)	UNLOCKING (pin is drawing in)

### Feedback signal on BROWN wire

LOCK'S STATUS	FEEDBACK SIGNAL
LOCKED	VCC(+)
UNLOCKED OR PIN MOVING OUT	GND(-)

## Operational mode

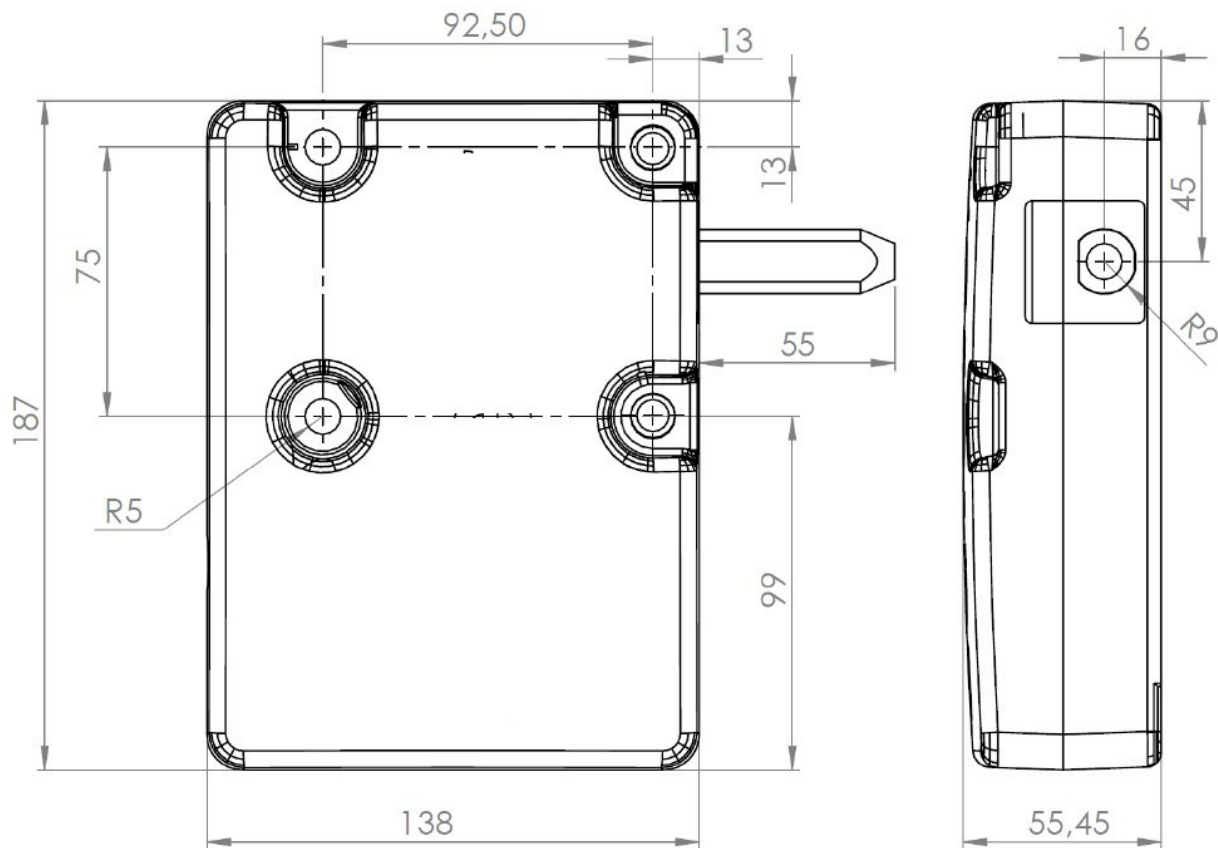
The Electronic Lock reacts with the control signal placed on the Signal Input (Blue wire). If the command (control signal) is changed during pin travel, the Electronic Lock has only acknowledged the new command ten seconds after the movement of the pins completed.

## Specification

Parameter	Unit	Value
Power supply voltage	V DC	12-24 ( 9-28)
Operational temperature	°C	Minus 30_Plus 65
Minimum current for input signal level identification (VCC / GND)	mA	20
Maximum current supported by gear-motor assembly	A	10 (at 24V)
Electronic current limit for gear-motor	mA	600
Current draw in non operational mode	mA	14 (13,8 VDC)
Current draw in non operational mode	mA	20 (28,2 VDC)
Rated current draw in operation (pin is moving)	mA	1200 (13,8 DC)
Rated current draw in operation (pin is moving)	mA	650(28,2 VDC)
<b>Dimensions &amp; weight</b>		
Pin maximum length	mm	56
Pin diameter	mm	18
Pin length when drawn out	mm	55
Pin length when drawn in	mm	4,5
Weight	kg	1,5

## Mounting





A special part of the design is its locking structure. Its holes are coated in steel, and this allows:

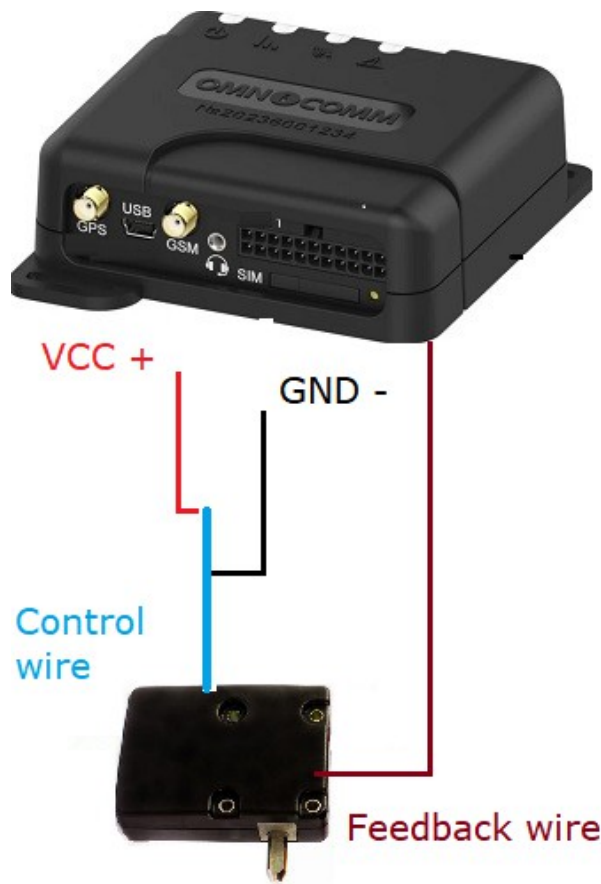
1. Increased mechanical resistance to screw tightening during clamping.
2. Increased structural resistance against frontal, lateral impacts by load movements.
3. Possibility of using a drill directly in the holes, thus eliminating the need to use jig.

The mounting method is defined by installer in every case and the following fasteners are usually used (are not supplied in set with actuator and supplied by installer from local market):

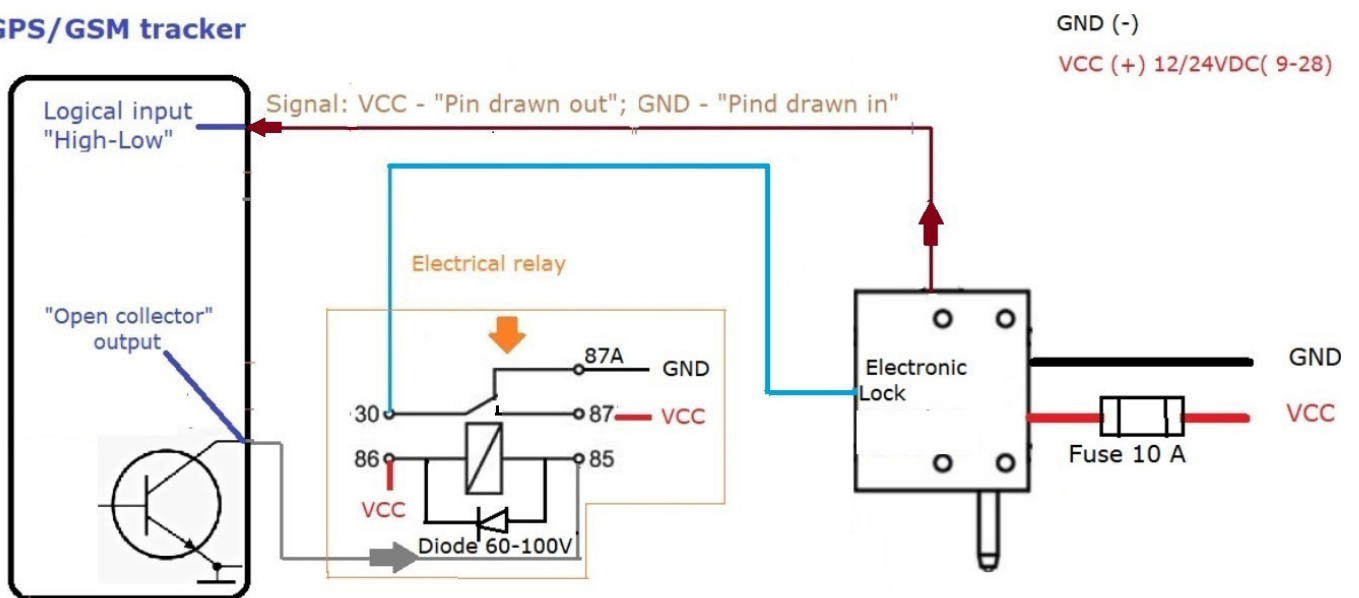
1. M8 screw
2. M8 screwed rivets
3. Blind rivets
4. Washers
5. Grover pucks
6. Mounting plates (steel or aluminum)
7. Polymer spiral protection for electrical wire.

**! Use high quality grade fasteners**

## Connection to the telematics device



### GPS/GSM tracker



## Extra parts and materials for installation



Relay image



Fasteners for mounting

## Contact us

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